

# Example: the language TINY

---

- Two kinds of constructs: expressions (**E**) and commands (**C**)
- Both constructs can contain identifiers (**I**)—strings of letters and digits beginning with a letter

## Syntax of TINY:

$E ::= 0 \mid 1 \mid \text{true} \mid \text{false} \mid I \mid \text{not } E \mid E_1 = E_2 \mid E_1 + E_2$

$C ::= I := E \mid \text{output } E \mid \text{if } E \text{ then } C_1 \text{ else } C_2 \mid$   
 $\text{while } E \text{ do } C \mid C_1; C_2$

# Standard semantics

---

- Denotational semantics is not able to handle constructs of real languages like
  - jumps, or
  - aliasing (multiple names of one variable).
- Therefore, more sophisticated denotations are needed—*standard semantics* is used.
- Standard semantics is based on
  - transforming states indirectly via *continuations*,
  - splitting the binding of identifiers to values into two parts:  $\text{id} \rightarrow \text{variable}$ ,  $\text{variable} \rightarrow \text{value}$ .

# Direct semantics vs. continuation semantics

---

- Denotational semantics is an example of *direct semantics*.
- In direct semantics:
  - each construct *directly* denotes its input/output transformation;
  - the transformation of the complete program is a combination of its components' transformations;
  - the result of a construct is always passed to the rest of the program  $\Rightarrow$  the rest of the program has to cope with abnormal values  $\Rightarrow$  it is stuffed with test for these values.

# Direct semantics vs. continuation semantics

---

- In continuation semantics:
  - denotation of a construct depends on the rest of the program—or *continuation*—following it;
  - each construct decides for itself where to pass its result:
    - usually to the *normal continuation* (corresponds to the textually following code);
    - to the continuation corresponding to an error stop;
    - to the continuation corresponding to the code following a label, target of a jump.

# Continuations

---

- A continuation is a function from an intermediate result expected by the rest of the program (e.g. state, or value–state pair) to the *final answer* (e.g. state + error, or output + error).
- *Command continuations* correspond to the rest of the program following a command and form a domain  
**Cont = State → [State + {error}]**
- *Expression continuations* correspond to the code following expressions and form a domain  
**Econt = Value → State → [State + {error}]**

# Continuation denotations of constructs

---

- In a continuation semantics the denotations of constructs are functions of continuations and states.
- The continuation semantic functions are of type:  
 $E: \text{Exp} \rightarrow \text{Econt} \rightarrow \text{State} \rightarrow [\text{State} + \{\text{error}\}]$   
 $C: \text{Com} \rightarrow \text{Cont} \rightarrow \text{State} \rightarrow [\text{State} + \{\text{error}\}]$   
and they are defined so that:

$$E[E] k s = \begin{cases} k v s' & \text{E has value } v, \text{ transforms } s \text{ to } s' \\ \text{error} & \text{otherwise} \end{cases}$$

$$C[C] c s = \begin{cases} c s' & \text{if } C \text{ transforms } s \text{ to } s' \\ \text{error} & \text{otherwise} \end{cases}$$

# Sample semantic clauses of TINY

---

- Domains

**State = Memory  $\times$  Input  $\times$  Output**

**Memory = Ide  $\rightarrow$  [Value + {unbound}]**

**Input = Value<sup>\*</sup>**

**Output = Value<sup>\*</sup>**

**Value = Num + Bool**

**Cont = State  $\rightarrow$  [State + {error}]**

**Econt = Value  $\rightarrow$  Cont**

- Functions

**E: Exp  $\rightarrow$  Econt  $\rightarrow$  Cont**

**C: Com  $\rightarrow$  Cont  $\rightarrow$  Cont**

# Sample semantic clauses of TINY

---

- Expressions:

$E [0] k s = k 0 s$ , or by canceling  $s$ :  $E [0] k = k 0$

$E [\text{read}] k (m,i,o) = \text{null } i \rightarrow \text{error}, k (\text{hd } i) (m,\text{tl } i,o)$

$E [l] k (m,i,o) = (m \text{ l} = \text{unbound}) \rightarrow \text{error}, k (m \text{ l}) (m,i,o)$

$E [\text{not } E] k s = E [E] (\lambda v s' . \text{isBool } v \rightarrow k (\text{not } v) s',$   
 $\text{error}) s$

- Commands:

$C [l := E] c = E [E] (\lambda v (m,i,o) . c (m[v/l],i,o))$

$C [\text{output } E] c = E [E] (\lambda v (m,i,o) . c (m,i,v.o))$

$C [C_1; C_2] c s = C [C_1] (C [C_2] c) s$



# Final answer of the program

---

- A state as the final answer of running a program is unnatural. In practice, it is just output.
- Once outputted information should not be retrieved by the rest of the program  $\Rightarrow$  the output must not be passed to it as a member of state.
- Once outputted information must not be lost, if an error occurs (probe **C [output 0] c** with  $c = \lambda s.error$ ).
- An output of a program need not be finite. Consider the nonterminating program

**x:=0; while true do (output x; x:=x+1)**

Its output is 0.1.2.3...

# Final answer of the program

---

- New domain equations are:

**State = Memory  $\times$  Input**

**Memory = Ide  $\rightarrow$  [Value + {unbound}]**

**Input = Value\***

**Value = Num + Bool**

**Cont = State  $\rightarrow$  Ans**

**Econt = Value  $\rightarrow$  Cont**

**Ans = {error, stop} + [Value  $\times$  Ans]**

- The semantic clause for output has to be changed:

**C [output E] c = E [E] ( $\lambda v s . (v, c s)$ )**

# Sharing

---

- Sometimes distinct identifiers can denote the same variable  $\Rightarrow$  assigning to one of them will change the value of the others.
- Sharing may occur:
  - directly—as the result of explicit command or declaration, e.g. **let**  $l_1 == l_2$ .
  - indirectly—e.g. (in PASCAL) by declaring a procedure of the form  
**procedure P(var x:real, var y:real)...**  
and executing a call **P(z,z)**.  
Both  $x$  and  $y$  share the variable denoted by  $z$ .

# Locations

---

- Sharing is enabled by two-level association between identifiers and values:
  1. an identifier is bound to a variable,
  2. the variable is bound to a value.
- In formal semantics, the term *location* is used rather than *variable*.
- Locations are modeled by the domain **Loc**.
- The only structure on **Loc** is  $=: \mathbf{Loc} \times \mathbf{Loc} \rightarrow \mathbf{Bool}$  which tests locations for equality.

# Stores

---

- *Stores* model the binding of locations to values.
- The domain **Store** is defined as
$$\mathbf{Store} = \mathbf{Loc} \rightarrow [\mathbf{Sv} + \{\mathbf{unused}\}]$$
where **Sv** is a domain of *storable values*.
- The function **new: Store**  $\rightarrow$  [**Loc** + {**error**}] returns an unused location, or error, if an unused location is not available.
- The notation  $v_1, \dots, v_n / i_1, \dots, i_n$  denotes the “little” store:
$$\lambda i . i = i_1 \rightarrow v_1, \dots, i = i_n \rightarrow v_n, \mathbf{unused}$$

# Environments

---

- *Environments* model binding of identifiers.
- The domain **Env** of environments is defined as
$$\mathbf{Env} = \mathbf{Ide} \rightarrow [\mathbf{Dv} + \{\mathbf{unbound}\}]$$
typical members will be  $r, r', r_1, r_2$  etc.
- **Dv** is the domain of *denotable values*. Sometimes, it can identify with **Loc**, but for most languages it contains also constants, procedures etc.
- For  $d_1, \dots, d_n \in \mathbf{Dv}, l_1, \dots, l_n \in \mathbf{Ide}, r_1, r_2 \in \mathbf{Env}$  there are defined the following notations:
  - $d_1, \dots, d_n / l_1, \dots, l_n = (\lambda l . l = l_1 \rightarrow d_1, \dots, l = l_n \rightarrow d_n, \mathbf{unbound})$
  - $r_1[r_2] = (\lambda l . r_2 \mid = \mathbf{unbound} \rightarrow r_1 \mid, r_2 \mid)$

# Standard domains of values

---

- Unlike in TINY, in most languages we distinguish several value domains. The most important are:
  - *storable* values **Sv**—can be stored in locations; typical members will be  $v, v', v_1, v_2$  etc.;
  - *denotable* values **Dv**—can be denoted by an identifier in the environment; typical members will be  $d, d', d_1, d_2$  etc.;
  - *expressible* values **Ev**—results of expressions; typical members will be  $e, e', e_1, e_2$  etc.
- Other domains can also be needed, e.g. *outputable* values, *R-values* (domain **Rv**) etc.

# Declarations and scope

---

- *Declaration* binds an identifier to a certain location.
- *Scope* of a declaration are the parts of a code where the declaration holds. (It is also possible to speak about scope of an identifier.)
- Example: declaration **var**  $l = E$ . It's effect is:
  1. a new location, say  $i$ , is obtained;
  2.  $E$ 's value is stored in  $i$ ;
  3.  $i$  is bound to  $l$  in the environment.
- In standard semantics declarations change the environment and possibly the store. On the other side, command do only change the store.



# Standard domains of continuations

---

## Domain of command continuations $C_c$

- Definition:  $C_c = \text{Store} \rightarrow \text{Ans}$
- $\text{Ans}$  is a language-dependent domain of final answers
- Typical members will be  $c, c', c_1, c_2$  etc.

## Domain of expression continuations $E_c$

- Definition:  $E_c = \text{Env} \rightarrow \text{Store} \rightarrow \text{Ans}$  (or more neatly  $E_c = \text{Env} \rightarrow C_c$ )
- Typical members will be  $k, k', k_1, k_2$  etc.

## Domain of declaration continuations $D_c$

- Def.:  $D_c = \text{Env} \rightarrow \text{Store} \rightarrow \text{Ans}$  (or  $D_c = \text{Env} \rightarrow C_c$ )
- Typical members will be  $u, u', u_1, u_2$  etc.

# Standard semantic functions

---

- The following semantic functions are used:  
 **$E: \text{Exp} \rightarrow \text{Env} \rightarrow \text{Ec} \rightarrow \text{Store} \rightarrow \text{Ans}$**  for expressions,  
 **$C: \text{Com} \rightarrow \text{Env} \rightarrow \text{Cc} \rightarrow \text{Store} \rightarrow \text{Ans}$**  for commands, and  
 **$D: \text{Dec} \rightarrow \text{Env} \rightarrow \text{Dc} \rightarrow \text{Store} \rightarrow \text{Ans}$**  for declarations.
- The intuitive meanings are (omitting errors etc.):

**$E [E] r k s = k e s'$**        $e$  is  $E$ 's value in environment  $r$  and store  $s$ ,  $s'$  is the store after  $E$ 's evaluation.

**$C [C] r c s = c s'$**        $s'$  is the store after  $C$ 's execution in environment  $r$  and store  $s$ .

**$D [D] r u s = u r' s'$**        $r'$  consists of bindings specified in  $D$ ,  $s'$  results from  $D$ 's evaluation (with respect to  $r$  and  $s$ ).

# L and R values

---

- Consider  $l_1$  and  $l_2$  denoting locations  $i_1$  and  $i_2$  and the command  $l_1 := l_2$ . There are two possibilities:
  - location  $i_2$  is stored in location  $i_1$ , or
  - the *contents* of location  $i_2$  is stored in location  $i_1$ .
- The second case is the common one  $\Rightarrow$  in standard semantics we assume that expressions on the right of assignments have their values *dereferenced*—i.e. have their values looked up in the store if they are locations.

# L and R values

---

- The following terminology is used:
  - expression's *L-value* is a value needed on the left of an assignment—a location; it is obtained by  $E$  without any dereferencing.
  - expression's *R-value* is a value needed on the right of an assignment; it is (normally) obtained by dereferencing the value obtained by  $E$ .
- It is traditional to define new semantic functions  $L: \text{Exp} \rightarrow \text{Env} \rightarrow \text{Ec} \rightarrow \text{Cc}$  and  $R: \text{Exp} \rightarrow \text{Env} \rightarrow \text{Ec} \rightarrow \text{Cc}$  for obtaining L-values and R-values, respectively.

# Procedures

---

- **proc**  $l(l_1);C$ —declaration of procedure named  $l$  with formal parameter  $l_1$  and body  $C$ .
- $l(E)$ —call of the procedure  $l$ ;  $C$  is executed in an environment identical to the one in which the procedure was declared, except that  $l_1$  denotes the  $E$ 's value.
- The above type of evaluation is called *static binding*. There are also other types of bindings, e.g. *dynamic binding* using the *call time environment*.
- $E$  in  $l(E)$  is called the *actual parameter*.

# Procedures

- Domain of procedure values is  
 $\text{Proc} = C_c \rightarrow E_v \rightarrow \text{Store} \rightarrow \text{Ans}$  (or  $\text{Proc} = C_c \rightarrow E_c$ );  
 typical members will be  $p, p', p_1, p_2$  etc.
- Intuitively, if  $p \in \text{Proc}$  then:  
 $p \ c \ e \ s = c \ s'$  where  $s'$  is the store resulting from  
 execution of  $p$ 's body.
- The procedure declaration binds a procedure value to  
 an identifier as follows:  
 $D \ [\text{proc } l(l_1); C] \ r \ u = u \ (p/l)$ , where  $p = \lambda c e . C \ [C] \ r[e/l_1] \ c$
- The semantics of procedure call is:  
 $C \ [l(E)] \ r \ c \ s =$   
 $E \ [l] \ r \ (\lambda e_1 s_1. \text{isProc } e_1 \rightarrow E \ [E] \ r \ (\lambda e_2 s_2. e_1 \ c \ e_2 \ s_2) \ s_1, \text{error}) \ s$

# Functions

- Notice that function calls, unlike procedure calls, are expressions and also function bodies are expressions.
- Domain:  $\text{Fun} = E_c \rightarrow E_c$   
Typical members will be  $f, f', f_1, f_2$  etc.
- The semantics of function declaration is:  

$$D [\text{fun } l(l_1); E] r u = u (f/l), \text{ where } f = \lambda k e . E [E] r [e/l_1] k$$
- The semantics of function call is:  

$$E [l(E)] r k s =$$

$$E [l] r (\lambda e_1 s_1. \text{isFun } e_1 \rightarrow E [E] r (\lambda e_2 s_2. e_1 k e_2 s_2) s_1, \text{error}) s$$
- Notice that Proc and Fun are denotable values, i.e. their members have to be in  $Dv$ .