
External Memory

Types of External Memory

- Magnetic Disk
 - Fixed disc
 - Removable disc
 - RAID
- Optical
 - CD-ROM
 - CD-Recordable (CD-R)
 - CD-R/W Compact Disc-ReWritable
 - DVD („Digital Versatile Disc,, or „Digital Video Disc")
- Magnetic Tape

DVD

- DVD (an abbreviation of "digital versatile disc,, or "digital video disc") is a digital optical disc storage format invented and developed by Philips, Sony, Toshiba, and Panasonic in 1995. The medium can store any kind of digital data and is widely used for software and other computer files as well as video programs watched using DVD players.

DVD Types

- One of the most common DVDs is the single-sided, single-layer disc, capable of holding 4.7 GB.
- The single-sided, double-layer disc is capable of holding between 8.5-8.7 GB.
- The double-sided, single-layer disc is capable of holding 9.4 GB.
- Although rare, the double-sided, double-layer disc is capable of holding up to 17.08 GB.
- At present: 25 GB / 50 GB.

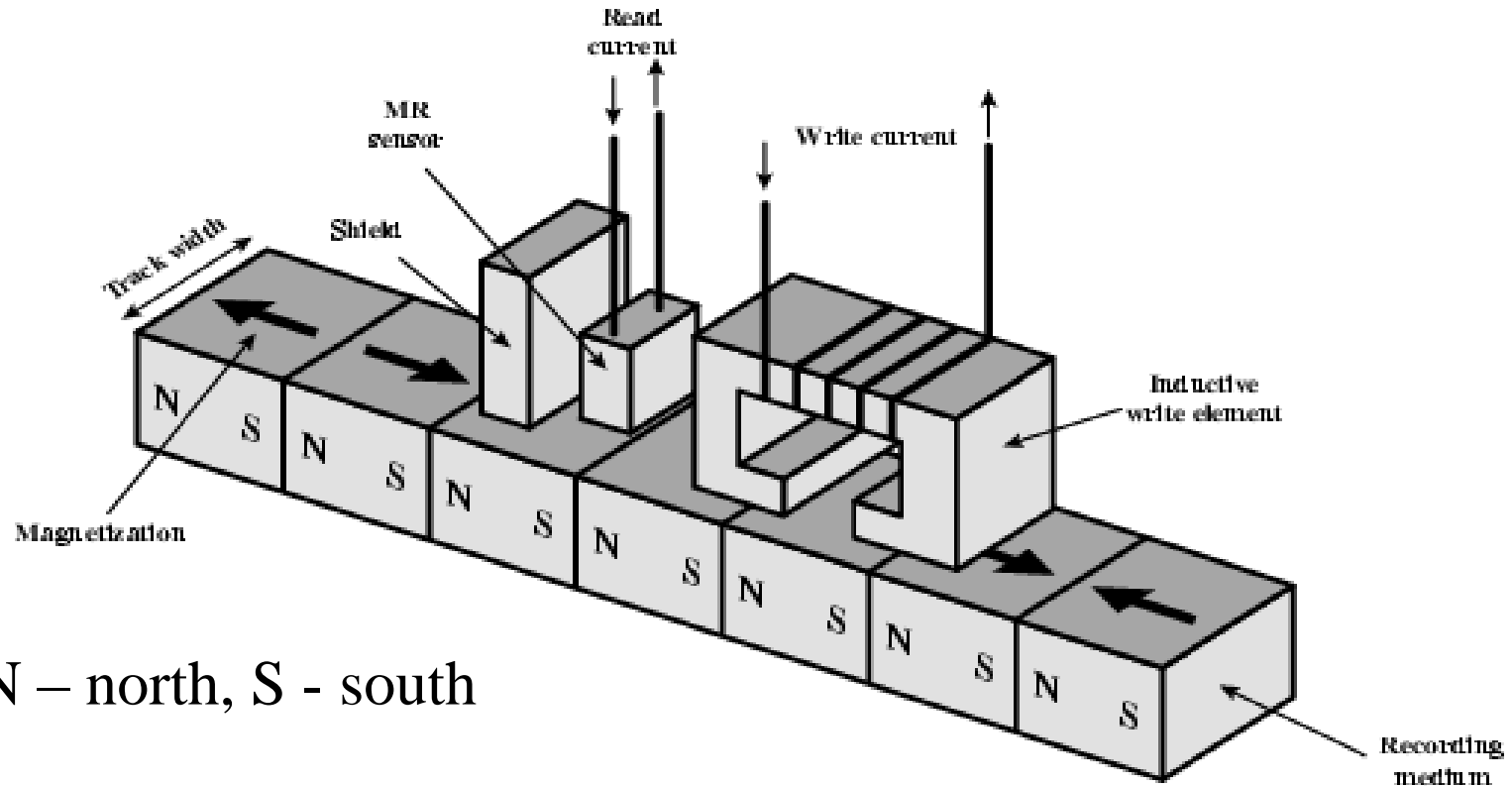
Magnetic Disk

- Disk substrate coated with magnetisable material (iron oxide).
- Substrate used to be aluminium.
- Now glass
 - Improved surface uniformity
 - Increases reliability
 - Reduction in surface defects
 - Reduced read/write errors
 - Lower flight heights
 - Better shock/damage resistance

Read and Write Mechanisms

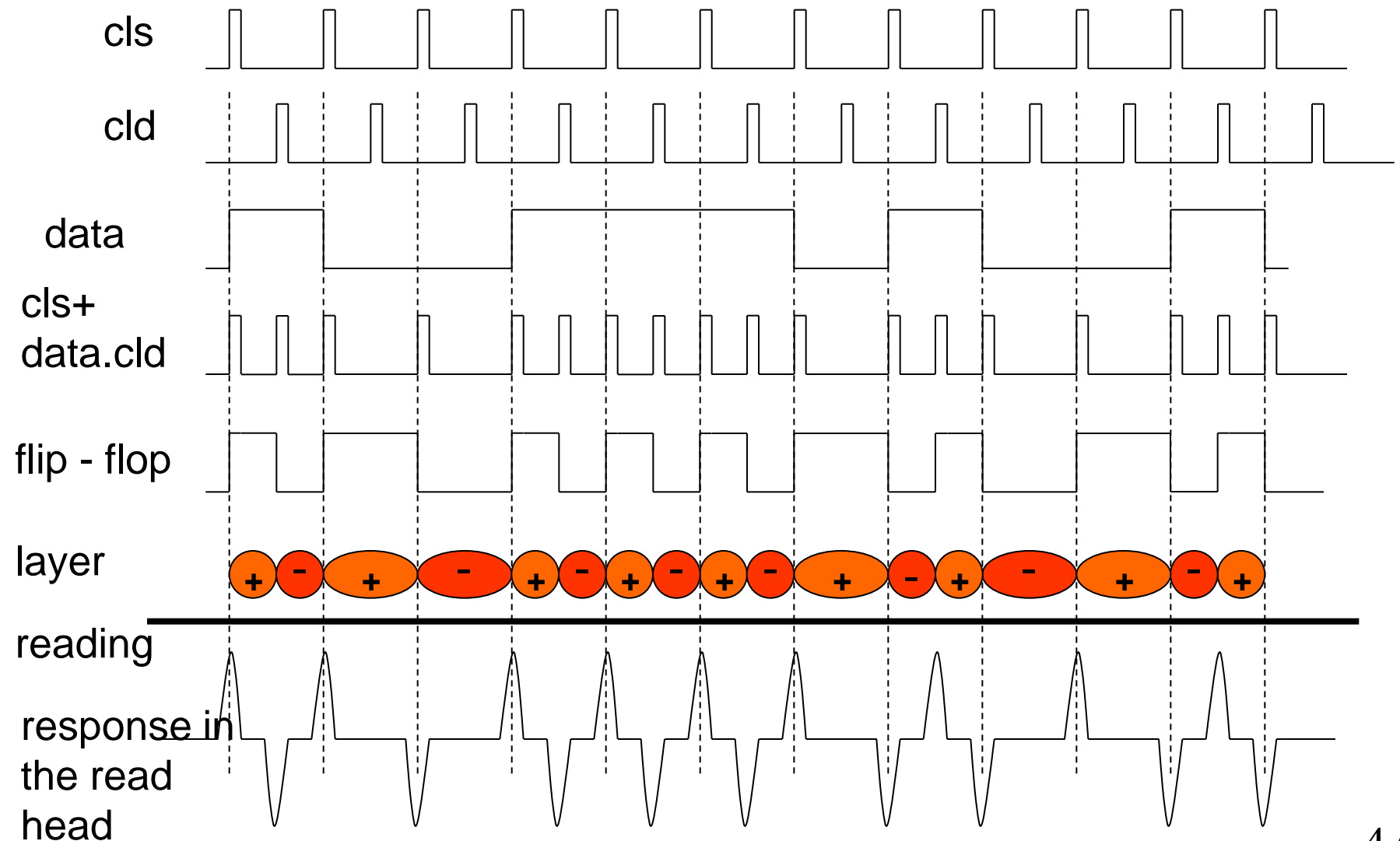
- Recording & retrieval via conductive coil called a head
- May be single read/write head or separate ones
- During read/write, head is stationary, platter rotates
- Write
 - Pulses sent to head
 - Current through coil produces magnetic field
 - Magnetic pattern is recorded on surface below head
- Read (traditional)
 - Magnetic field moving relative to coil induces voltage in head
 - Coil is the same for read and write
- Read (contemporary)
 - Separate read head, close to write head
 - Partially shielded magneto resistive (MR) sensor
 - Electrical resistance depends on the direction of magnetic field
 - High frequency operation
 - Higher storage density and speed

Inductive Write MR Read



N – north, S - south

FM recording (Frequency Modulation)

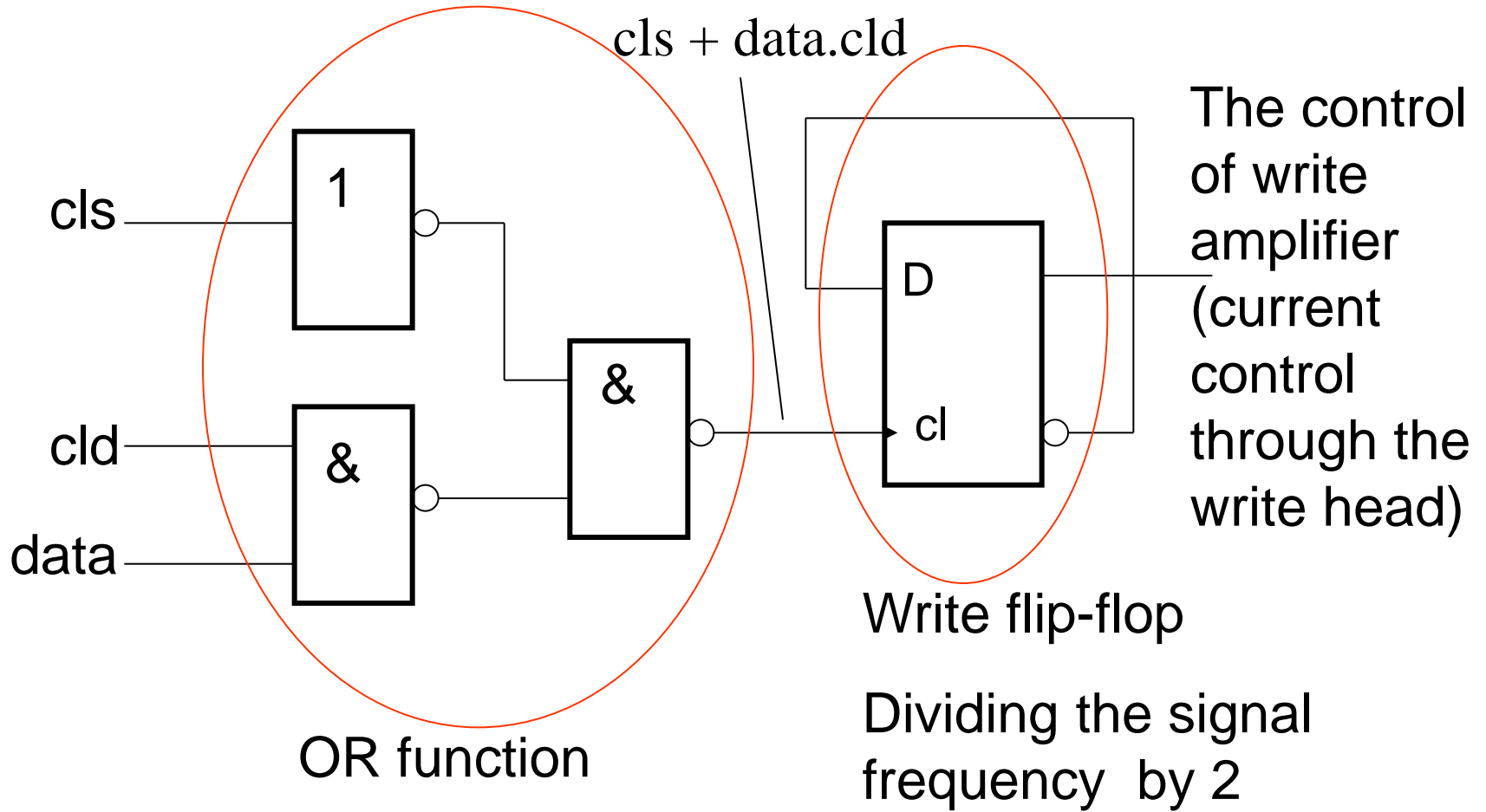


The principles of recording data in FM methodology

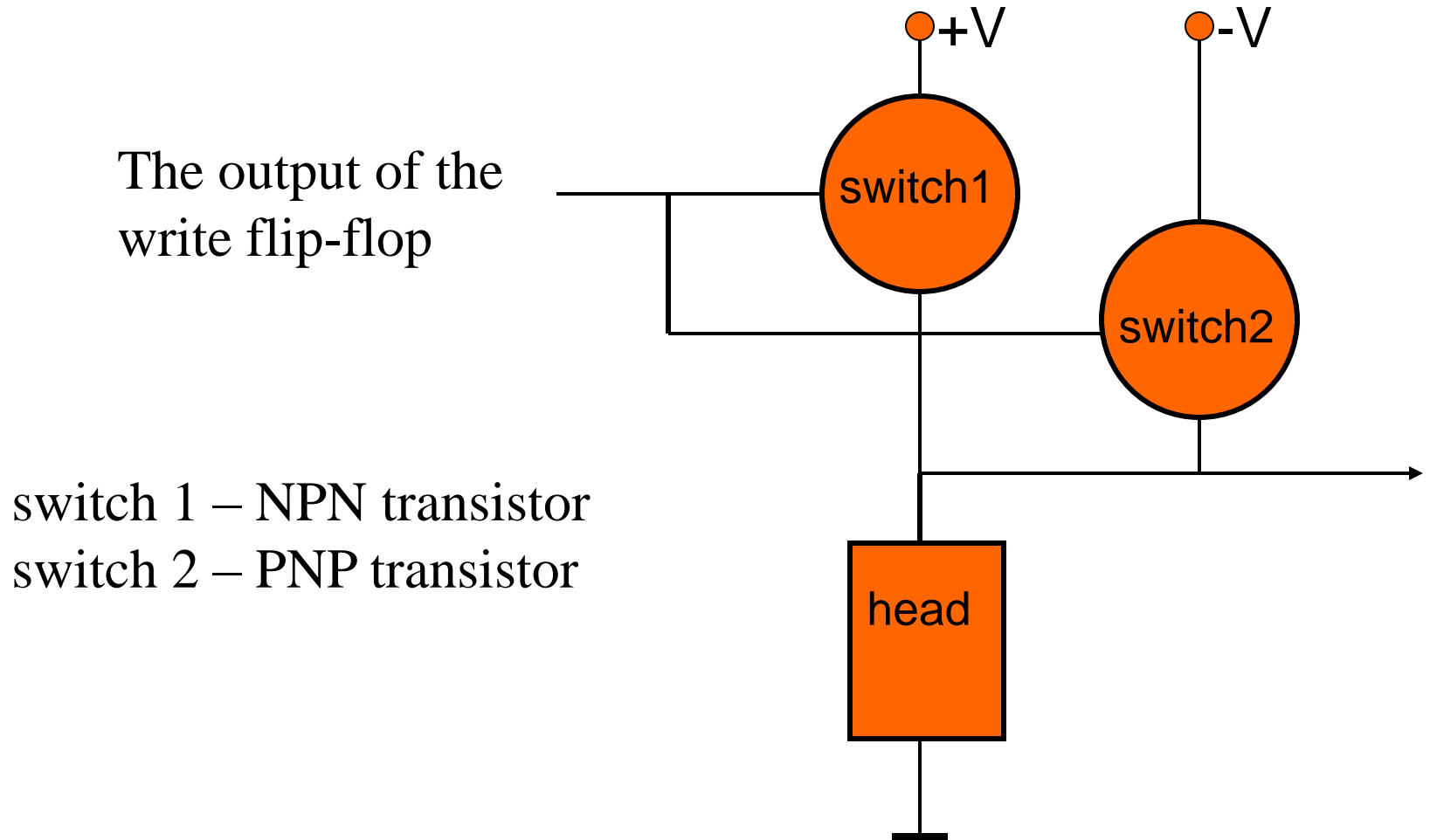
Recording „0“ – just c/s is included into the resulting signal

Recording „1“ – c/d is also included into the resulting signal, resulting in higher frequency of recorded signal (2x) – the worst sample of data.

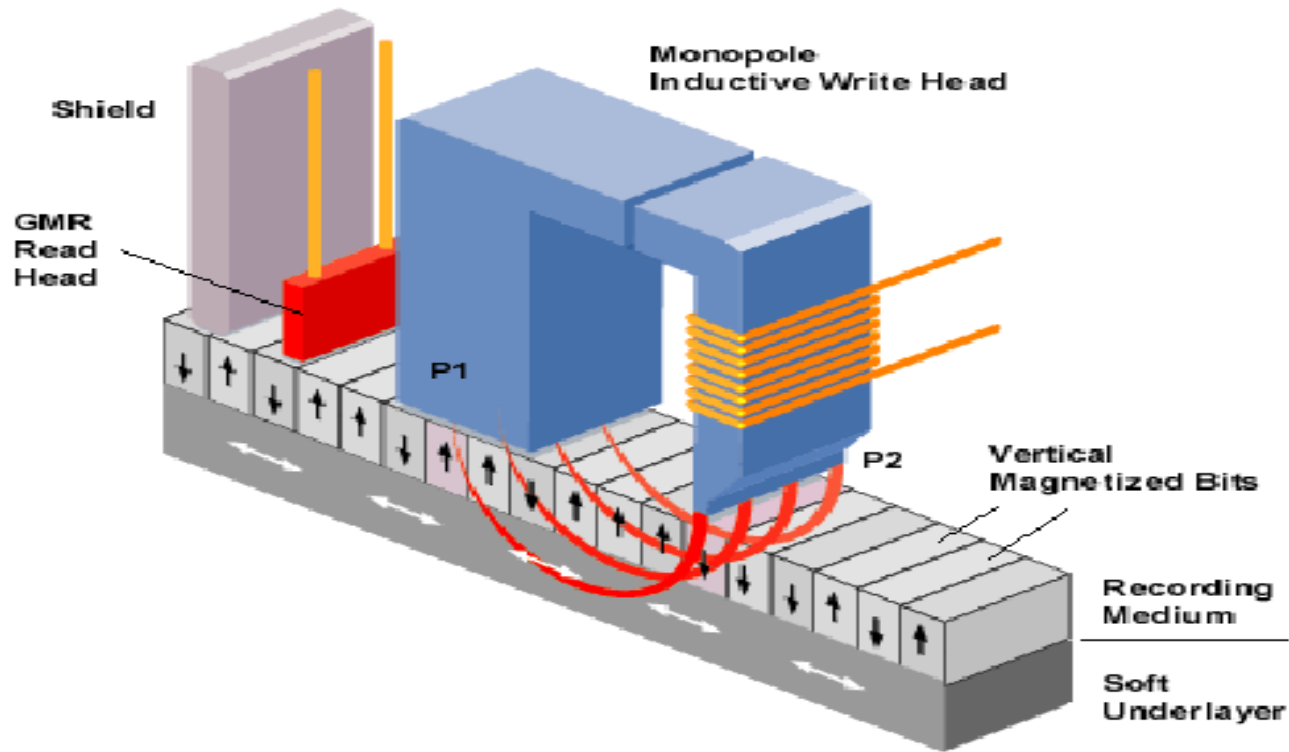
Encoding data for write procedure



Control of the current through the head during write operation



Perpendicular Magnetic Recording - PMR

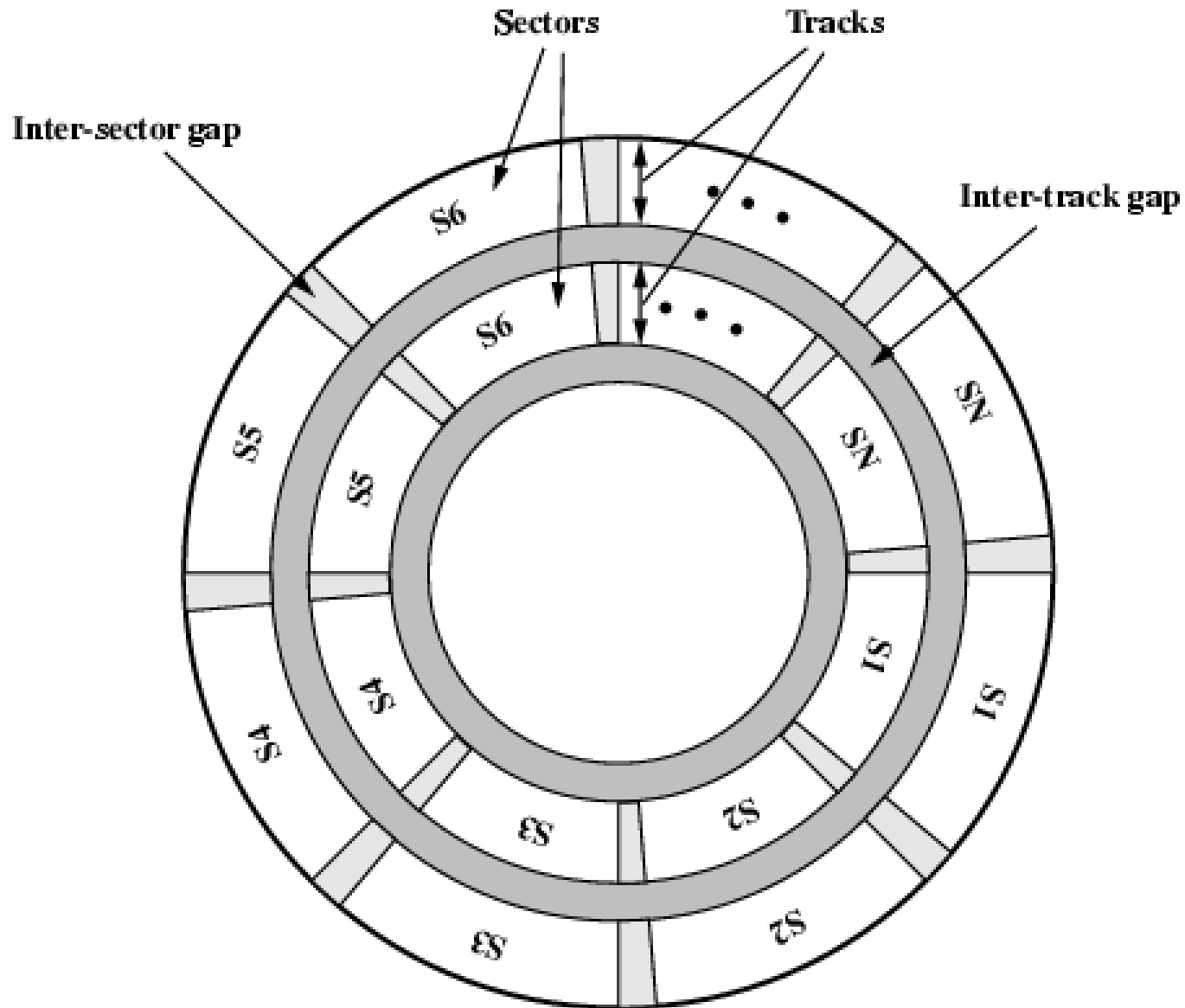


By means of PMR, significantly higher capacity can be reached.

Data Organization and Formatting

- Concentric rings or tracks
 - Gaps between tracks (track density)
 - Track density: 30 000 tracks per inch (TPI)
 - Reduced gap to increase capacity
 - Same number of bits per track (variable packing density) – not true now
 - Constant angular velocity
- Tracks divided into sectors.
- One sector is the minimum block size.

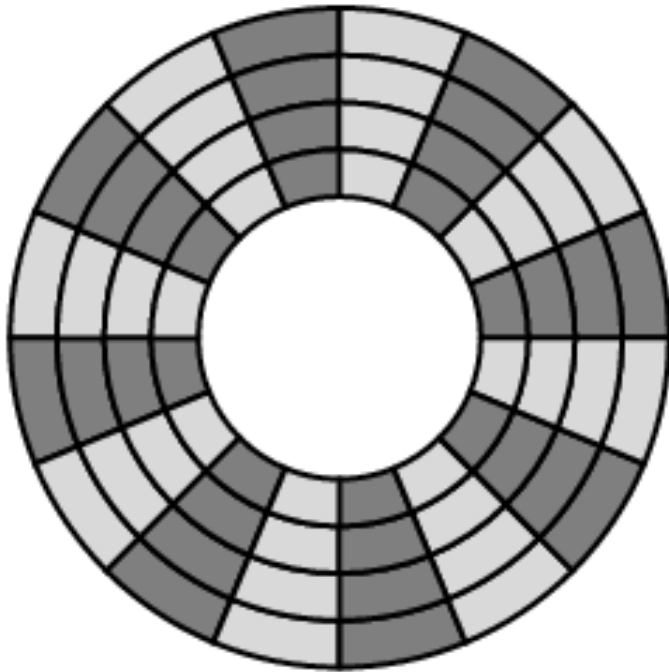
Disk Data Layout



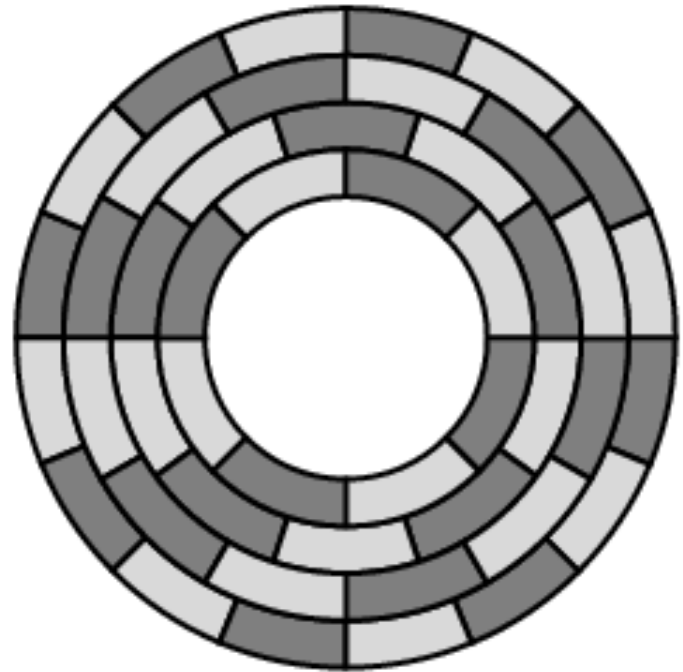
Disk Velocity

- Bit near centre of rotating disk passes fixed point slower than bit on outside of disk.
- Different spacing between bits in different tracks (linear density).
- Rotate disk at constant angular velocity (CAV)
 - Individual tracks and sectors addressable
 - Move head to given track and wait for the addressed sector
 - Waste of space on outer tracks
 - Lower data density
- Can use zones to increase capacity
 - Each zone has fixed number of bits per track
 - More complex circuitry

Disk Layout Methods Diagram



(a) Constant angular velocity



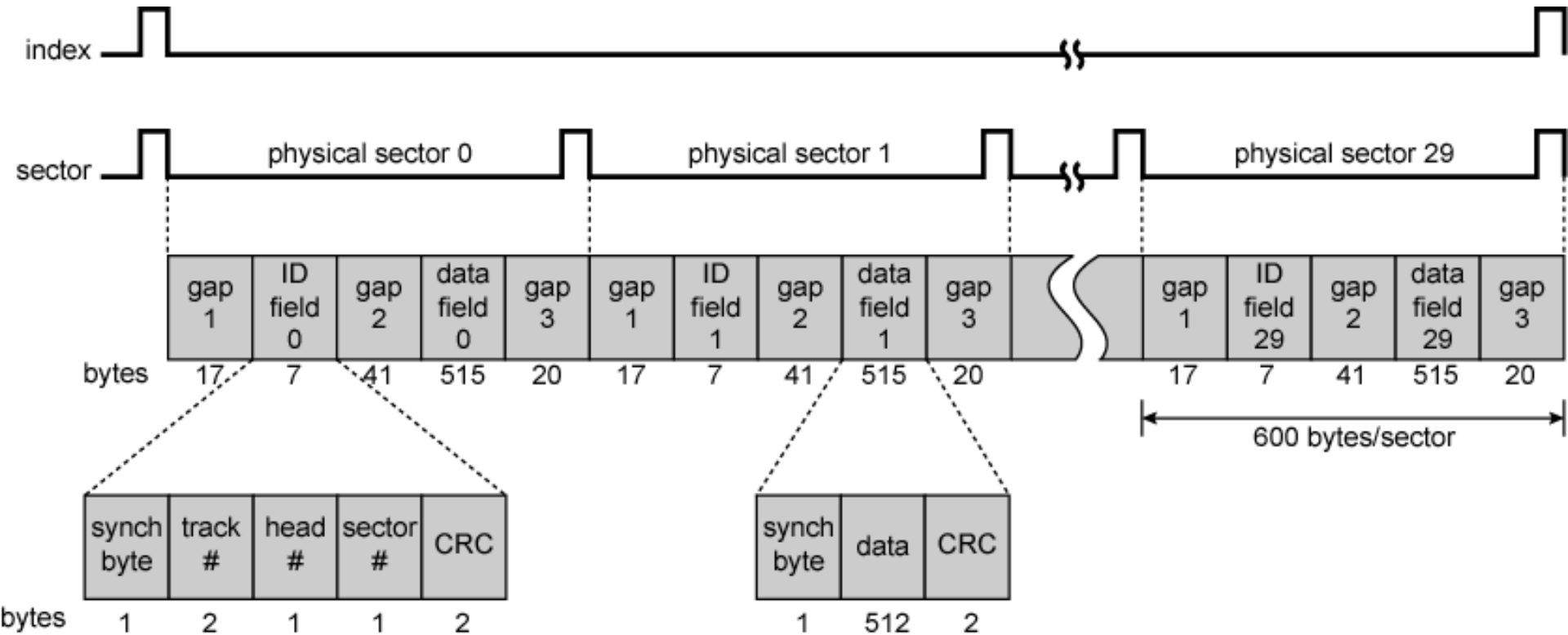
(b) Multiple zoned recording

Finding Sectors

- Must be able to identify start of track and sector.
- Format disk
 - Additional information not available to user
 - Marks tracks and sectors

Winchester Disk Format

Seagate ST506



Characteristics

- Fixed (rare) or movable head
- Removable or fixed disc
- Single or double (usually) sided
- Single or multiple platter
- Head mechanism
 - Contact (Floppy disc)
 - Fixed gap
 - Flying (Winchester disc)

Fixed/Movable Head Disk

- Fixed head
 - One read write head per track
 - Heads mounted on fixed arm
- Movable head
 - One read write head per side
 - Mounted on a movable arm

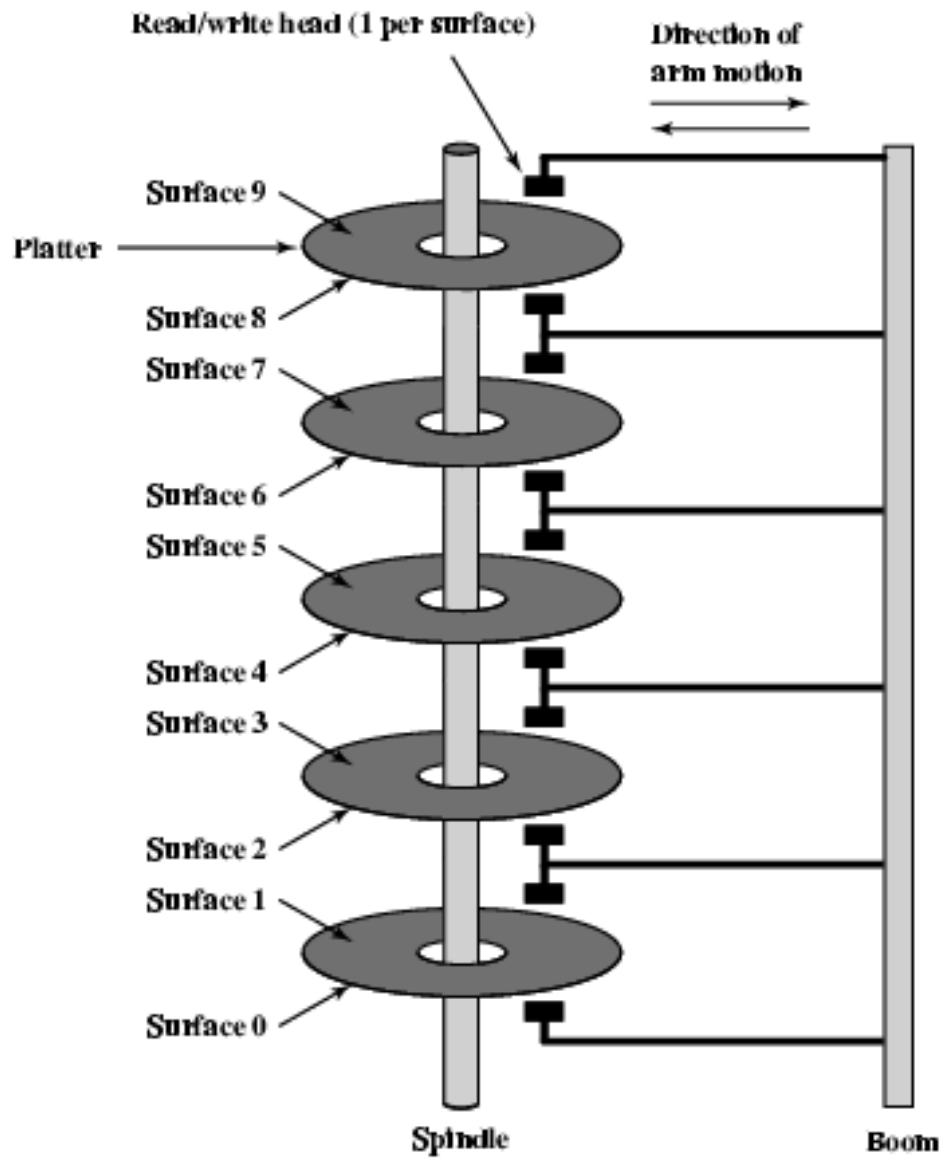
Removable or Not

- Removable disk
 - Can be removed from drive and replaced with another disc
 - Provides unlimited storage capacity
 - Easy data transfer between systems
- Non-removable disc
 - Permanently mounted in the drive

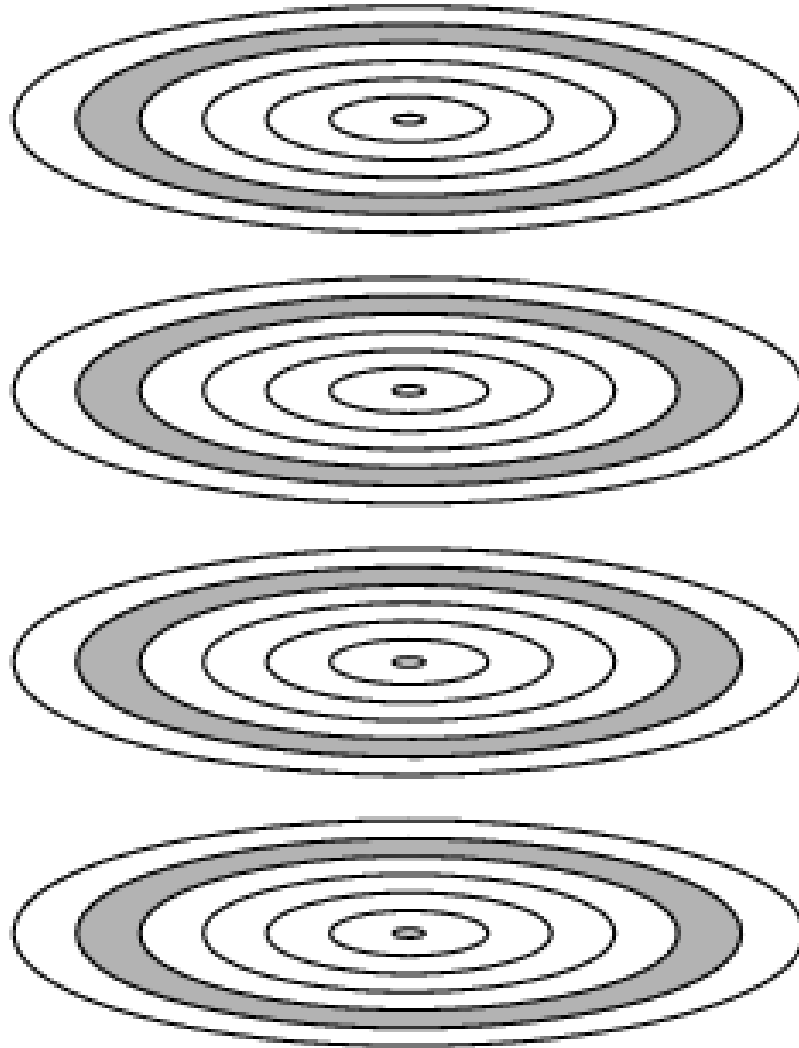
Multiple Platter

- One head per side
- Heads are joined and aligned together
- Aligned tracks on each platter form cylinders
- Data is organized into cylinders
 - it reduces head movement
 - it increases speed (transfer rate)

Multiple Platters



Tracks and Cylinders



Floppy Disk

- 8", 5.25", 3.5"
- Small capacity
 - Up to 1.44Mbyte (2.88M never popular)
- Slow
- Universal
- Cheap
- Obsolete, not used now.

Winchester Hard Disk (1)

- Developed by IBM in Winchester (USA).
- Sealed unit (disc is invisible).
- One or more platters (disks).
- Heads fly on boundary layer of air as disk spins.
- Very small head to disk gap.

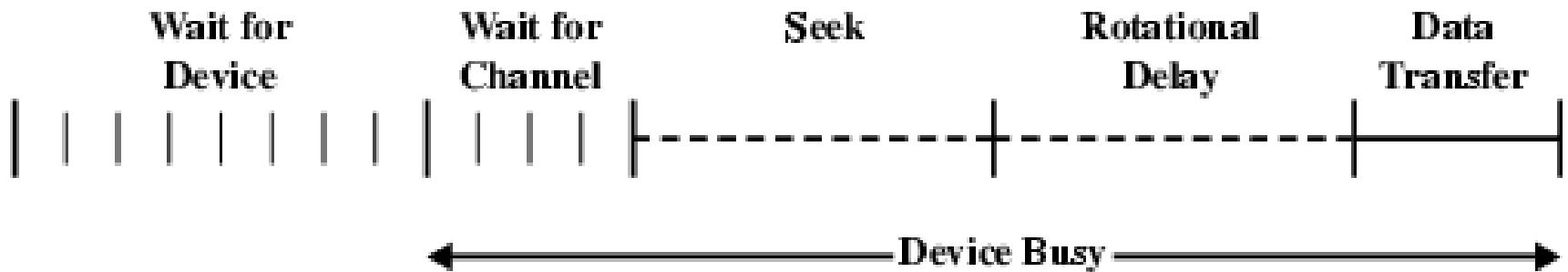
Winchester Hard Disk (2)

- Universal
- Cheap
- Fastest external storage
- Getting larger all the time
 - Terabytes now easily available (up to 10 TB)

Speed

- Seek time
 - Moving head to correct track
- (Rotational) latency
 - Waiting for data to rotate under head
- Access time = Seek time + Rotational delay
- Transfer rate

Timing of Disk I/O Transfer



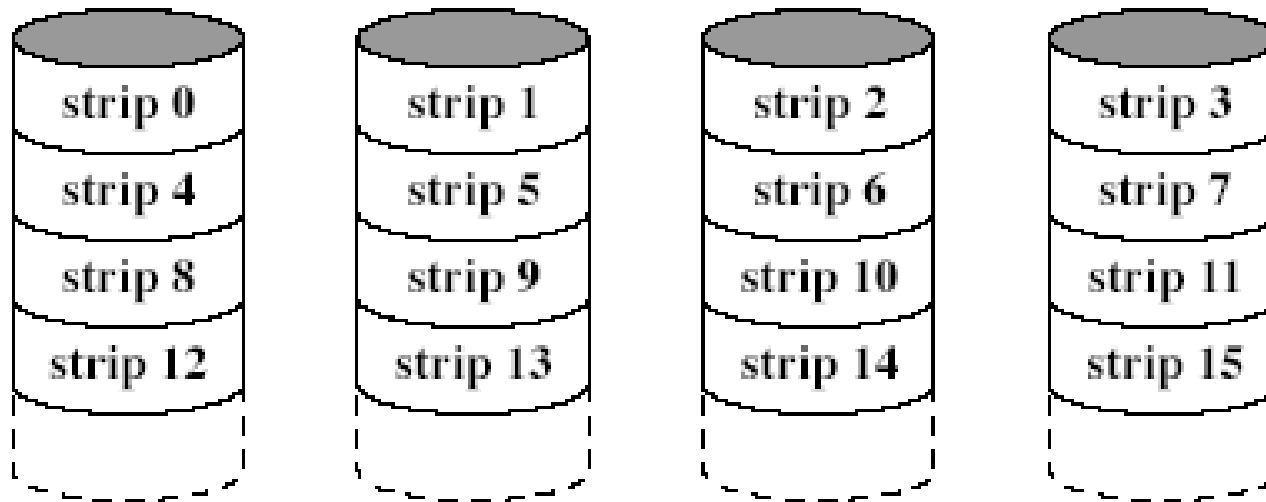
RAID Architectures

- Redundant Array of Independent Disks (correct).
- Redundant Array of Inexpensive Disks.
- 6 levels in common use.
- Not a hierarchy.
- The set of physical disks viewed by Operating System as single logical drive.
- Data distributed across physical drives.
- The architecture uses redundant capacity to store parity information.
- Two goals:
 - to reduce the access time
 - to increase reliability

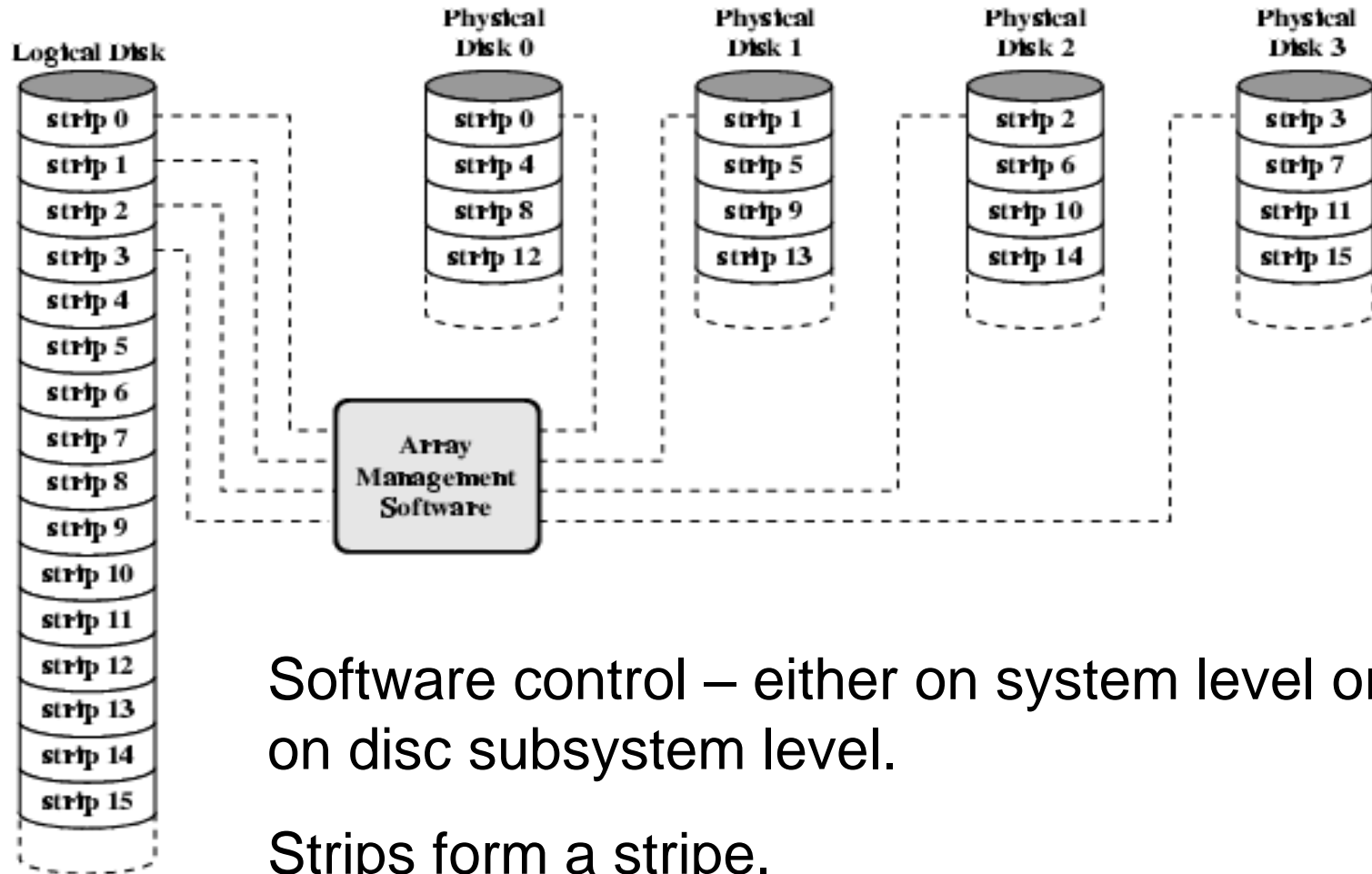
RAID 0

- No redundancy.
- Data striped across all disks.
- The increase of speed:
 - Multiple data requests not on the same disk.
 - Disks seek in parallel.
 - A set of data is striped across multiple disks.

RAID 0



Data Mapping for RAID 0



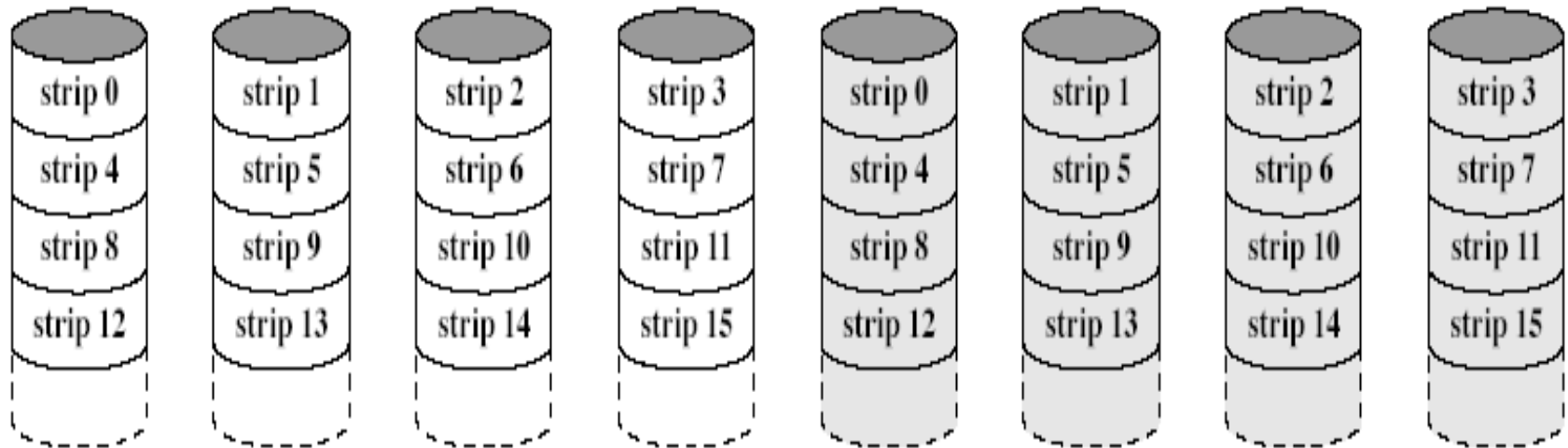
Software control – either on system level or on disc subsystem level.

Strips form a stripe.

RAID 0

- How the operating system cooperates with RAID disks:
 - the operating system generates „read“ command (data are organized in sequence on strips),
 - RAID controller divides the command to 4 separate commands and sends them to disc controllers,
 - the disc controllers perform the commands in parallel,
 - the best organization of data – data between which a link exists are stored in adjacent strips, i. e. in one stripe (e.g. a file) – data are transferred in parallel.

RAID 1



RAID 1

- Mirrored disks and backed up.
- Data is striped across disks.
- 2 copies of each stripe on separate disks.
- Read from either.
- Write to both.
- Recovery is simple
 - Swap faulty disk (install new disk) & re-mirror
 - No down time (one disk works permanently)
- Expensive.

RAID 1

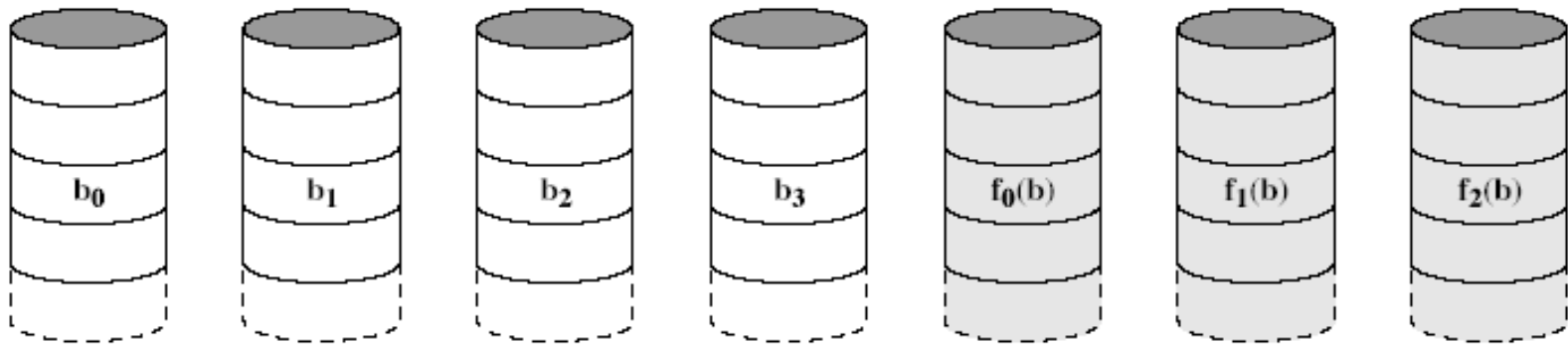
Read data operation – just from one disc (that one which will be faster in search for data (access time = seek time + rotational delay)).

Write data operation – performed in parallel to both discs → the performance during write operation will be strongly influenced by the slower disc.

Recovery after fault – data is read from the disc which operates correctly.

Disadvantage – high costs.

RAID 2

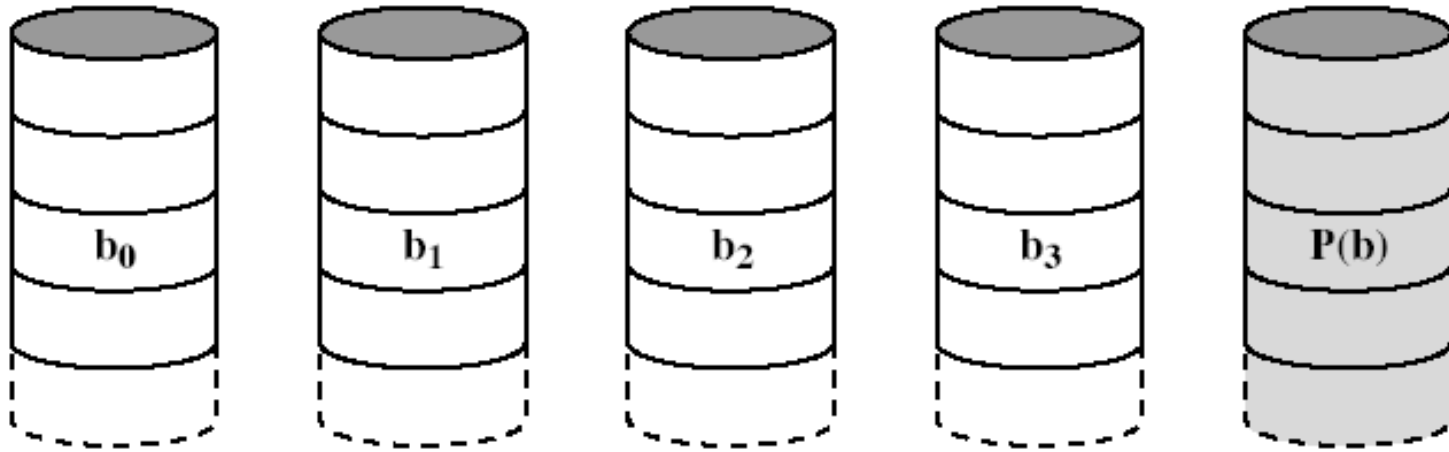


4 discs – data, 3 discs – information allowing to correct data

RAID 2

- The disks are synchronized – the heads are in the same position on all disks (cylinder, rotation).
- Parallel access – all disks are involved in processing I/O commands (they operate in parallel).
- Error correction calculated across corresponding bits on disks.
- Multiple parity disks store Hamming code error correction in corresponding positions.
- Lots of redundancy
 - Expensive
 - Not widely used

RAID 3



RAID 3

- Similar to RAID 2.
- Only one redundant disk, no matter how large the array.
- Simple parity bit for each set of corresponding bits.
- **Data on failed drive can be reconstructed from surviving data and parity info.**

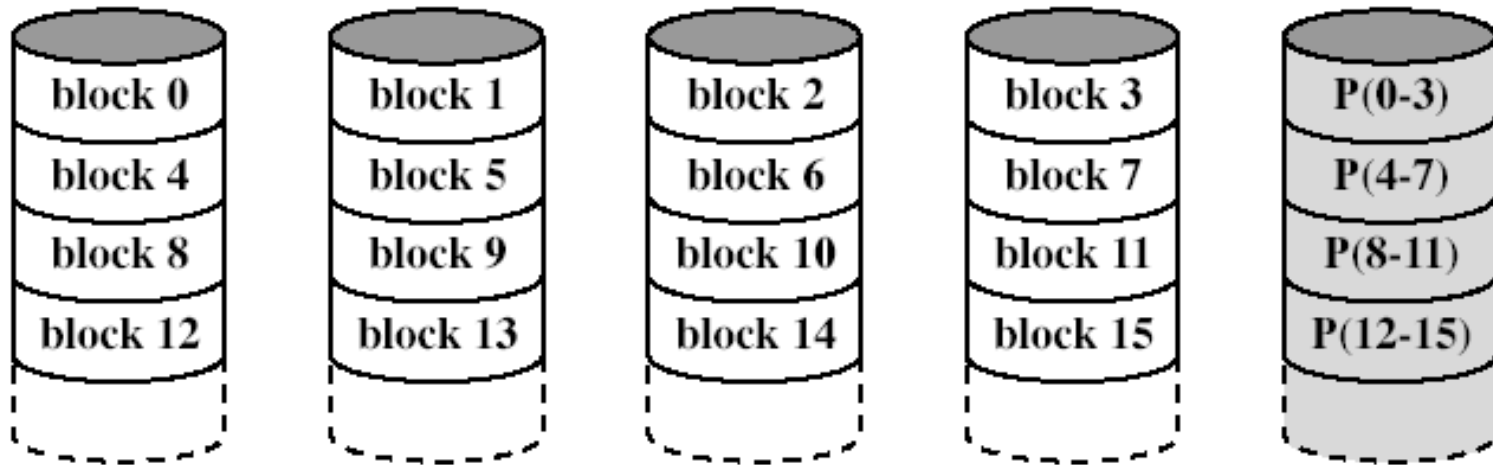
RAID 3

- If a fault appears on a disk, then parity bit is read and data are reconstructed from the remaining bits, the parity bit is used for the reconstruction with other bits.
- After the faulty disk is removed and non-faulty (i. e. new) disc installed, then data can be reconstructed from the remaining bits.
- Data reconstruction:
 - Let RAID system consists of 5 disks:
 - X0 – X3 - data
 - X4 – parity bit
- How the parity bit is calculated:
$$X4(i) = X3(i) \text{ xor } X2(i) \text{ xor } X1(i) \text{ xor } X0(i)$$

RAID 3

- An example: a failure appeared on disk X1, data stored are not available.
- The parity :
$$X4(i) = X3(i) \text{ xor } X2(i) \text{ xor } X1(i) \text{ xor } X0(i)$$
- To both sides of the equation $X4(i) \text{ xor } X1(i)$ is xored:
We receive:
$$X4(i) \text{ xor } X4(i) \text{ xor } X1(i) = X3(i) \text{ xor } X2(i) \text{ xor } X1(i) \text{ xor } X0(i) \text{ xor } X4(i) \text{ xor } X1(i),$$
- $X4(i) \text{ xor } X4(i)$ is always equal to 0, the same holds for $X1(i) \text{ xor } X1(i)$
- Then: $X1(i) = X4(i) \text{ xor } X3(i) \text{ xor } X2(i) \text{ xor } X0(i)$
- Thus, the value of the bit from the disk with failure is calculated from remaining bits.
- **The conclusion:** the value of the bit from the disc with a failure is derived from the remaining bits. This principle is used for RAID3 - RAID6 architectures.

RAID 4



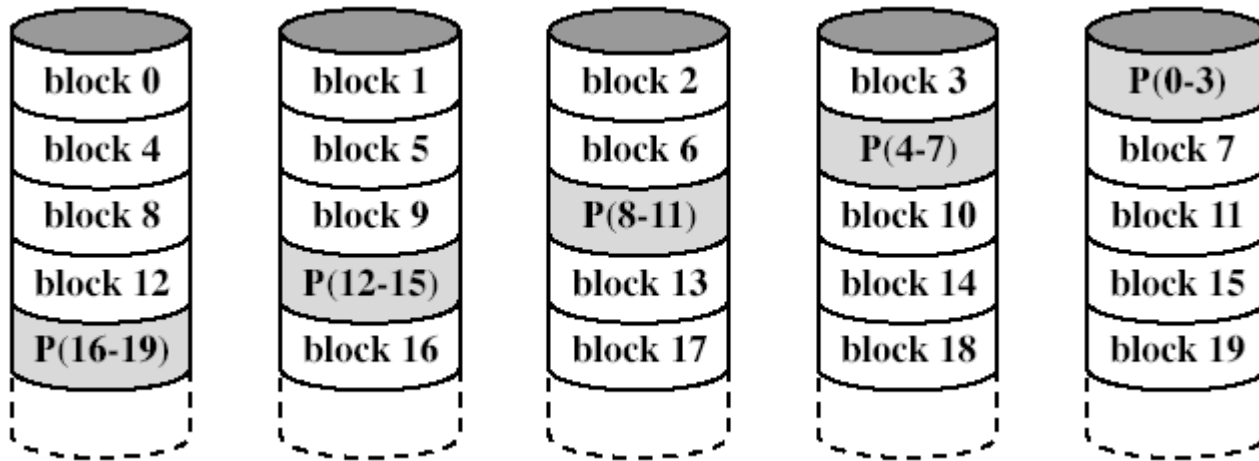
RAID 4

- Each disk operates independently
- Good for high I/O request rate
- Large stripes
- Bit by bit parity calculated across stripes on each disk
- Parity stored on parity disk

The use of redundancy for data recovery

- The situation: we need to write data to one disk only – how the parity written to disk is derived?
- The field consists of 5 disks: X0 – X3 – data, X4 – parity evaluated in the following way:
$$X4(i) = X3(i) \text{ xor } X2(i) \text{ xor } X1(i) \text{ xor } X0(i)$$
- How the new parity is evaluated when the value of bit X1 is changed:
$$\begin{aligned} X4'(i) &= X3(i) \text{ xor } X2(i) \text{ xor } X1'(i) \text{ xor } X0(i) = X3(i) \text{ xor } \\ &X2(i) \text{ xor } X1'(i) \text{ xor } X0(i) \text{ xor } X1(i) \text{ xor } X1(i) = \\ &= X3(i) \text{ xor } X2(i) \text{ xor } X1(i) \text{ xor } X0(i) \text{ xor } X1(i) \text{ xor } X1'(i) = \\ &= X4(i) \text{ xor } X1(i) \text{ xor } X1'(i) \end{aligned}$$
- The conclusion: to evaluate the new parity, then old parity value, original value and new value of the bit are used.
- To the disk data bit and parity are recorded.

RAID 5

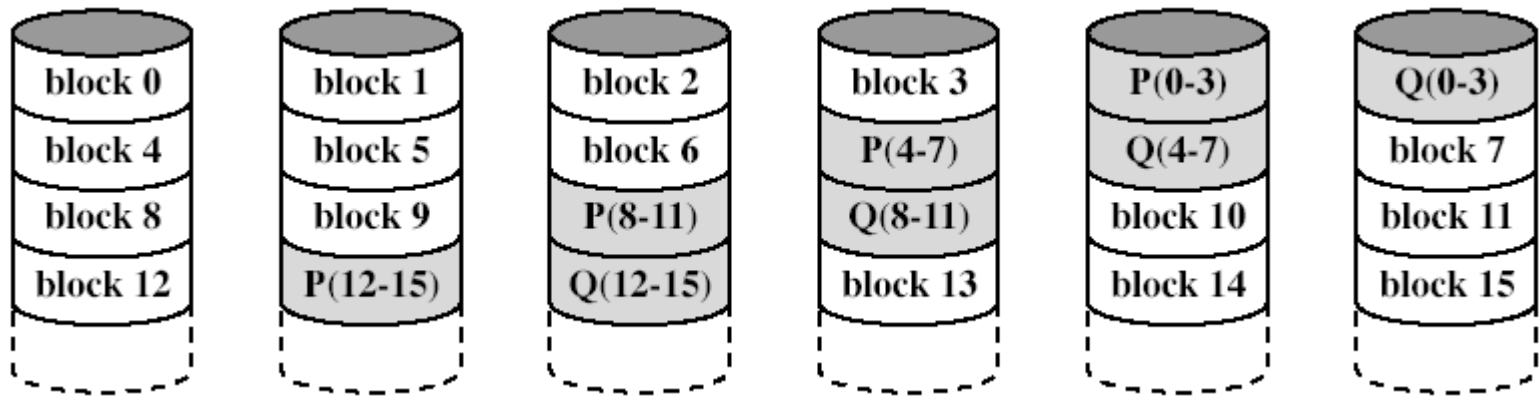


„block-level distributed“ parity type

RAID 5

- Like RAID 4.
- Parity striped across all disks.
- Avoids RAID 4 bottleneck at parity disk.
- Commonly used in network servers.

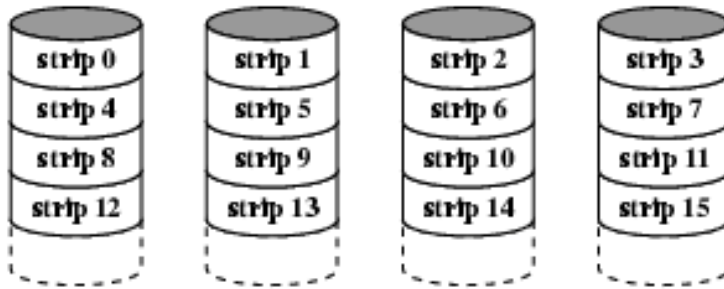
RAID 6



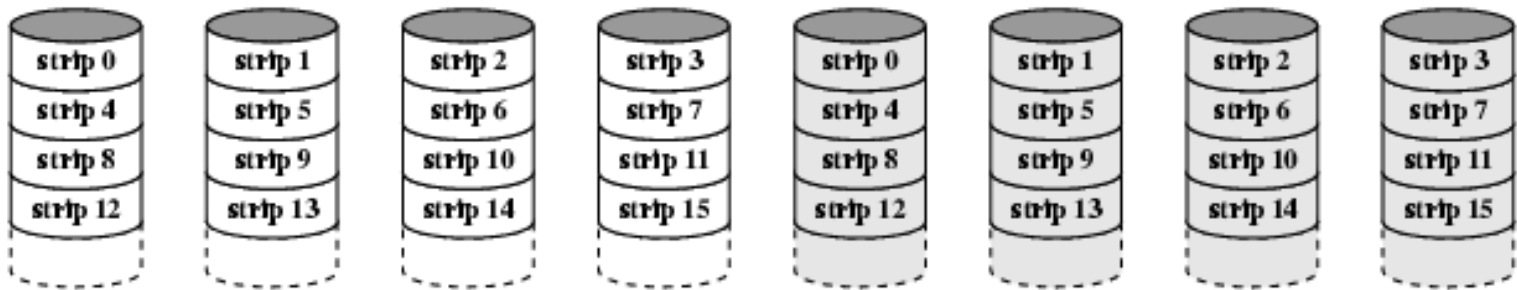
RAID 6

- Two parity calculations
- Stored in separate blocks on different disks
- User requirement of N disks needs $N+2$
- High data availability
 - Three disks need to fail for data loss
 - Significant write penalty

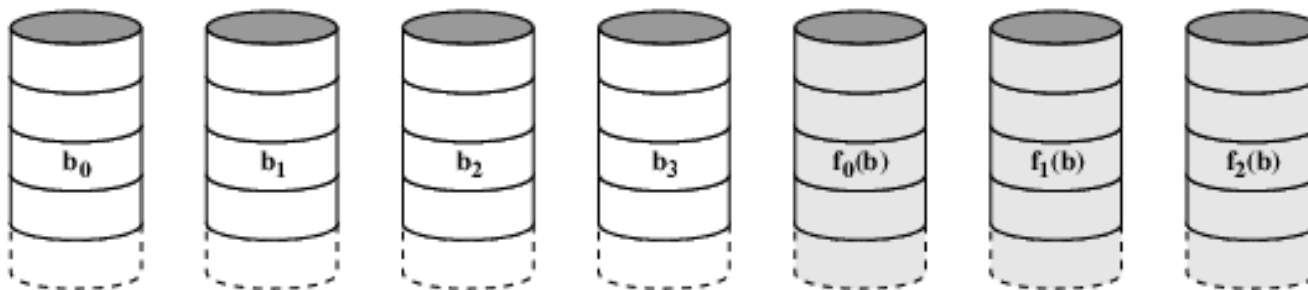
RAID 0, 1, 2



(a) RAID 0 (non-redundant)

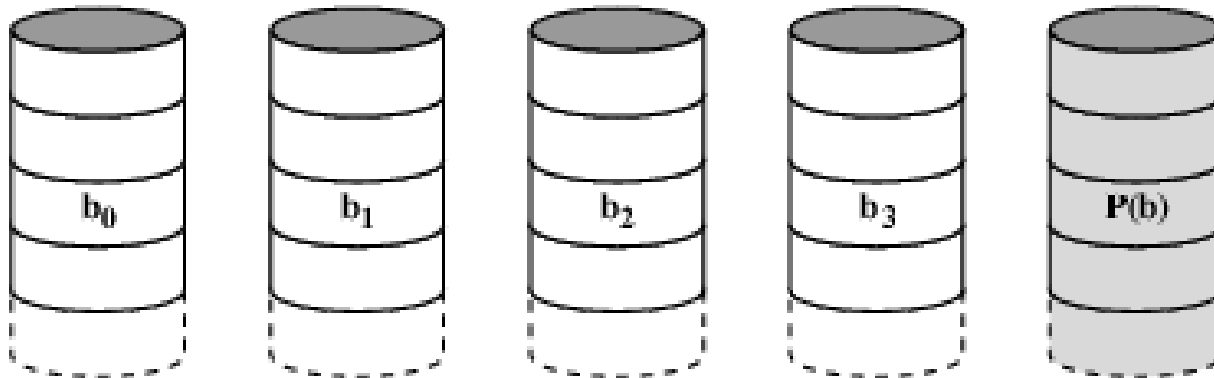


(b) RAID 1 (mirrored)

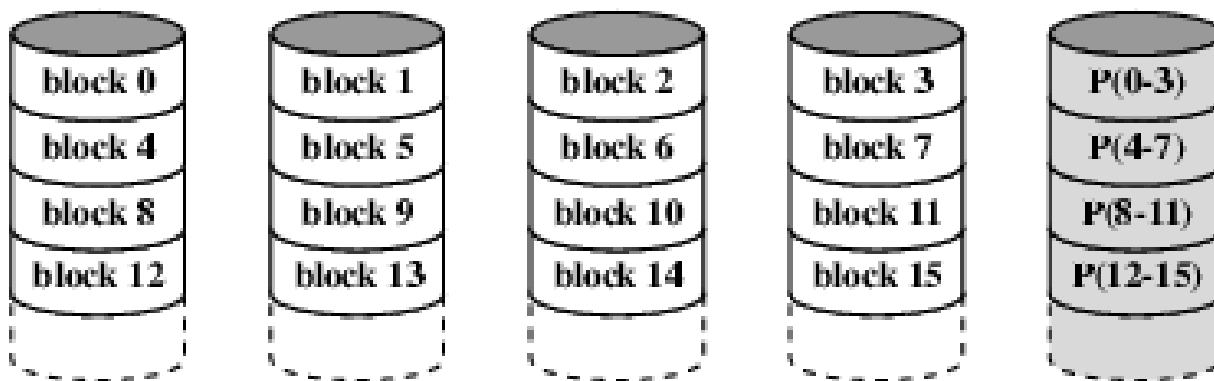


(c) RAID 2 (redundancy through Hamming code)

RAID 3 & 4

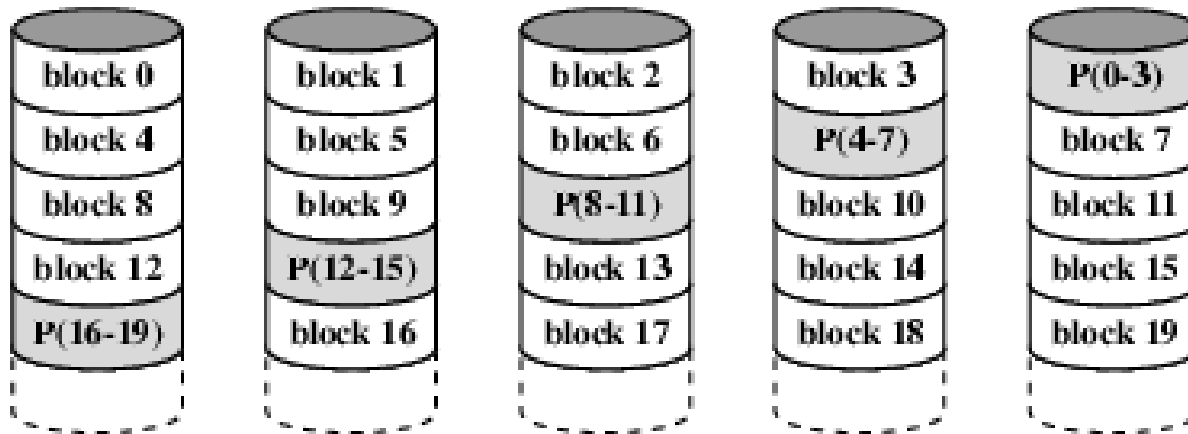


(d) RAID 3 (bit-interleaved parity)

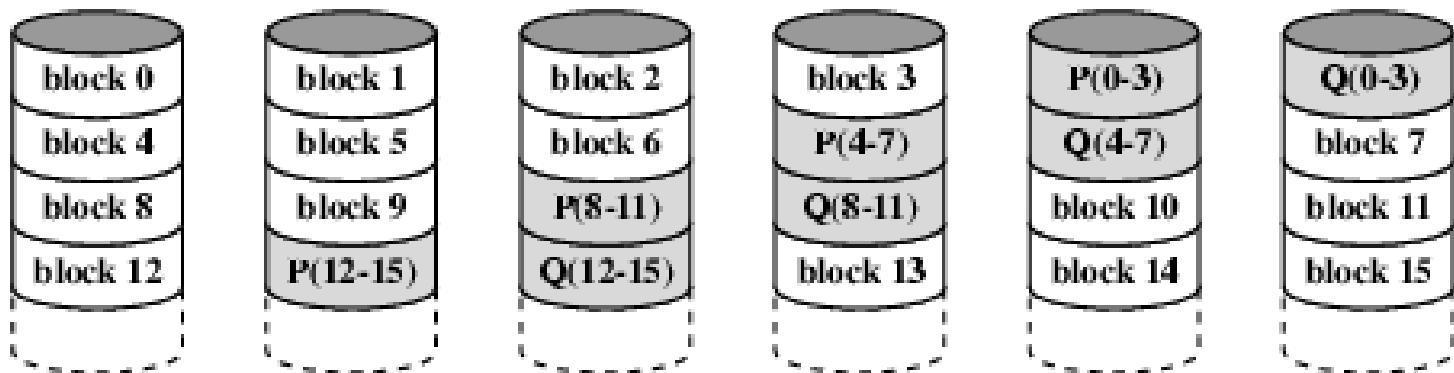


(e) RAID 4 (block-level parity)

RAID 5 & 6



(f) RAID 5 (block-level distributed parity)



(g) RAID 6 (dual redundancy)